
Anomaly detection in event-based manufacturing systems using model generation



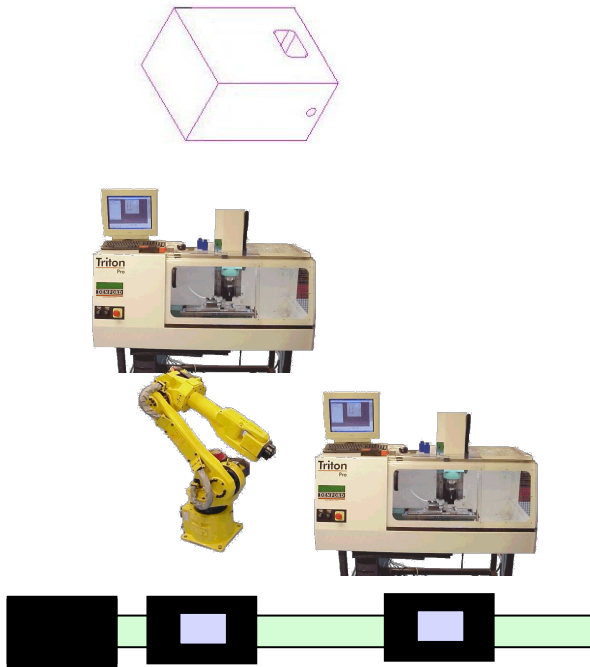
Dawn Tilbury

Professor, Mechanical Engineering, University of Michigan
Guest Professor, Automatic Control, Lund University

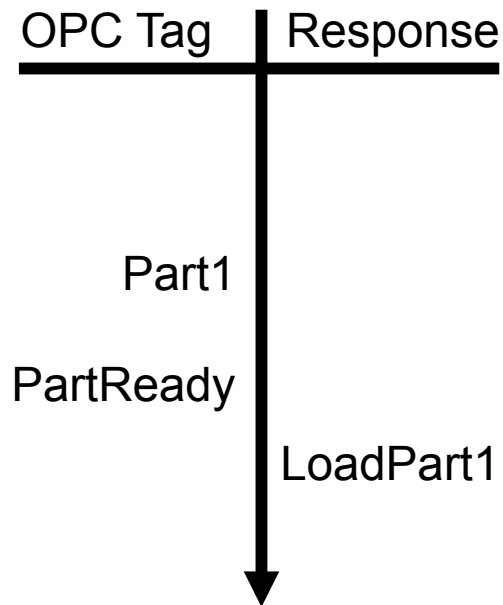
Outline

- **Motivating example**
- **Anomaly detection method**
- **Application to industrial system**
- **Conclusions and future work**

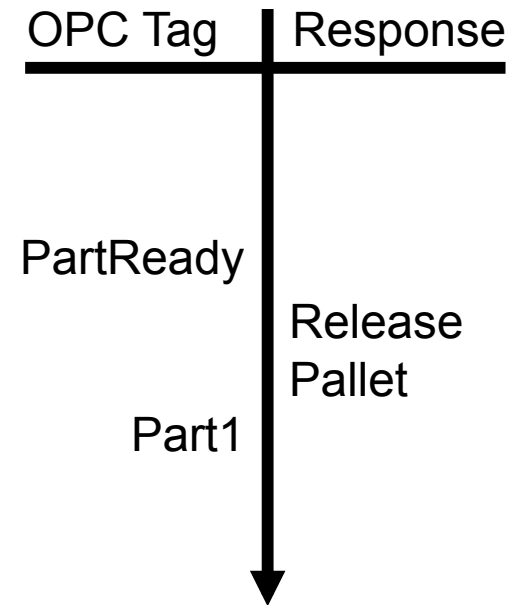
Motivating example



Correct, typical behavior

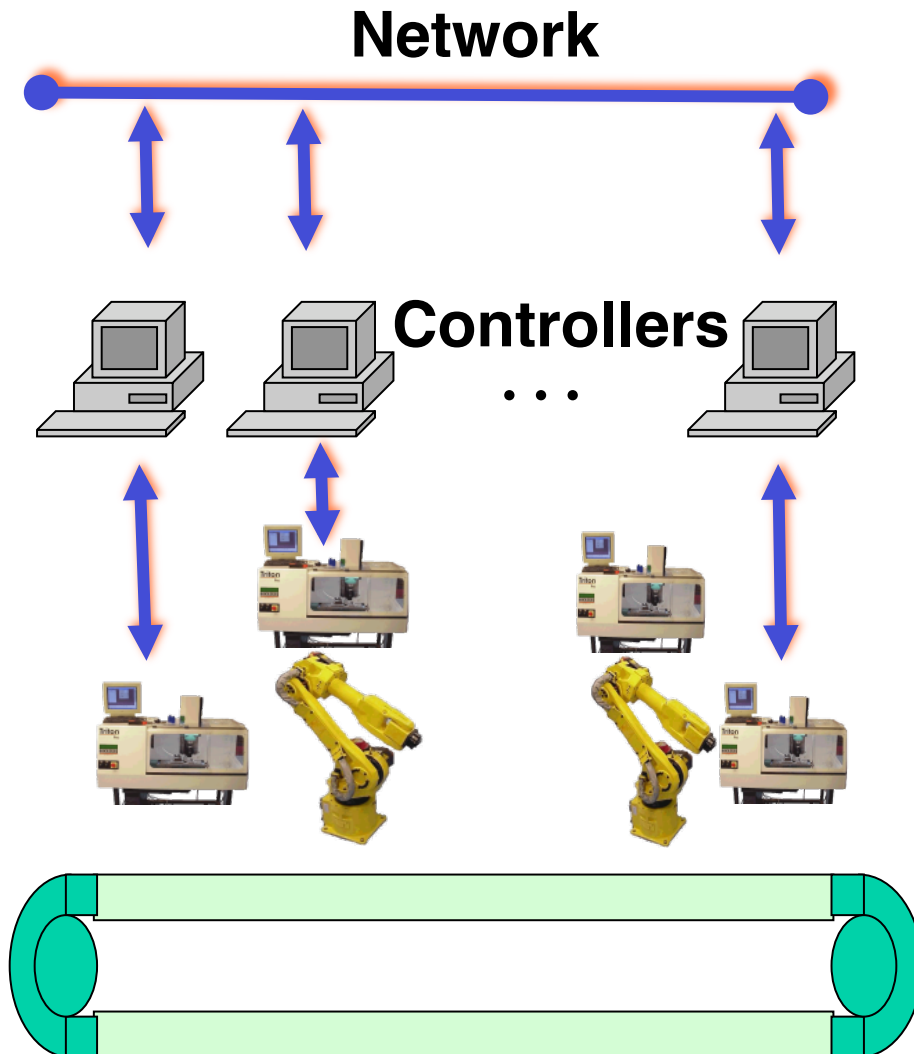


Incorrect behavior



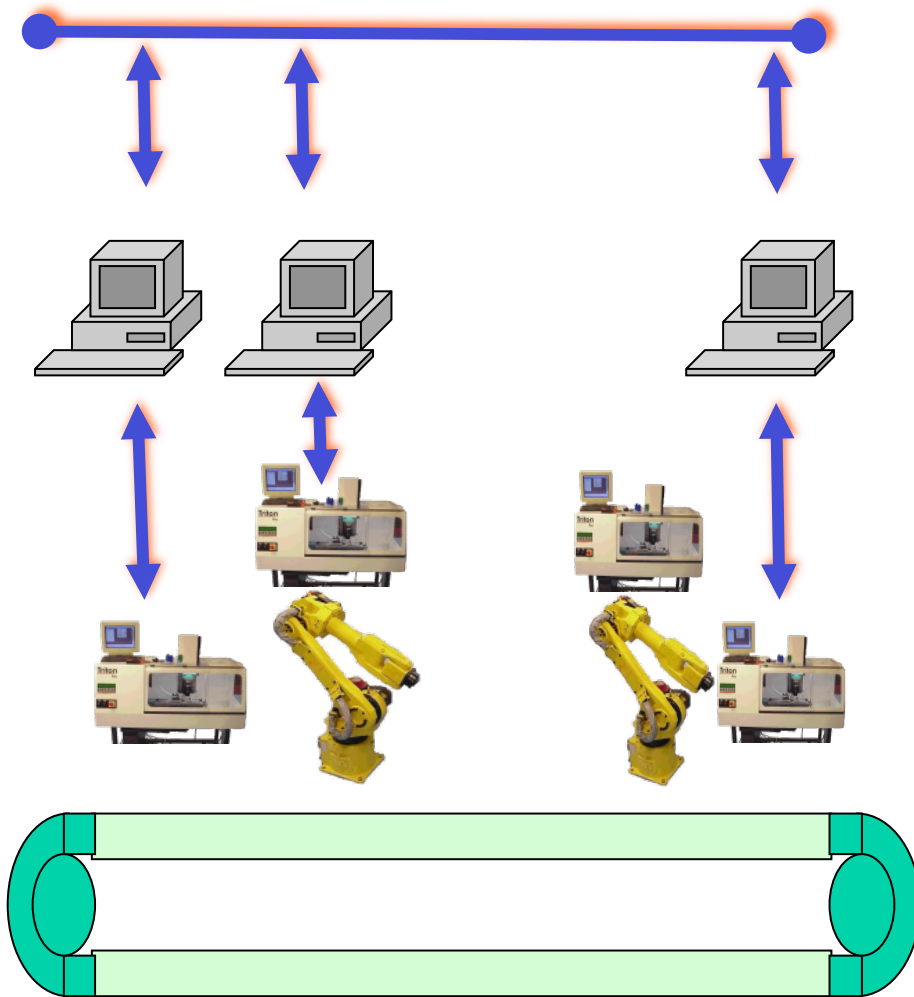
- No model of entire system's correct behavior
- Manual inspection to find the anomaly
 - a laborious, offline process

Manufacturing systems



- **Resource**
 - Robot, machine, conveyor, pallet ...
- **Controller**
 - machine control, system-level, PLC, ...
- **Communication**
 - Networks carry **events** between **controllers**
- **Process**
 - Set of disjoint **events**
 - Use shared **resources** to accomplish a goal

Problem statement



- Given a manufacturing system with known **resources** and **processes**, and a record of **events** sent between controllers,
- **Find anomalies** in the event-based communication records

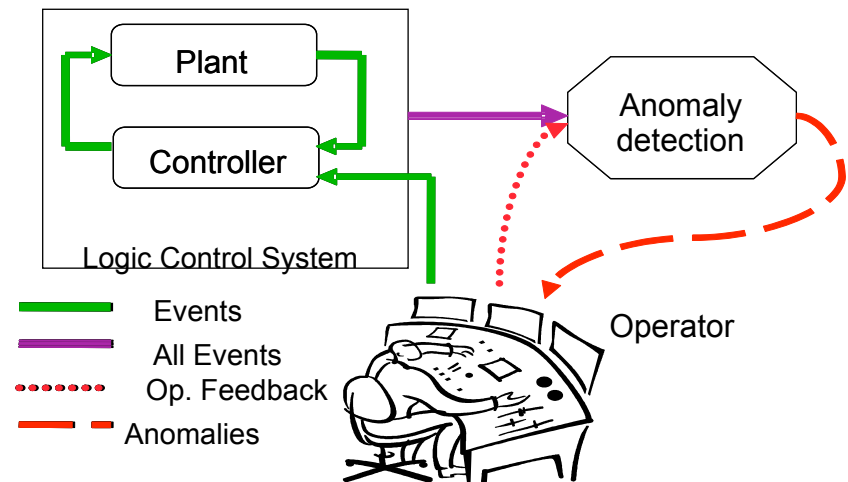
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Goal: Anomaly detection

- **Assumptions:**

- No formal model
- Resources are known
- Processes are known
- Events are recorded
 - Events associated with resources and processes



- **Method:**

- Generate models based on training data
- Detect anomaly by comparing trace to models
- Advise the operator when anomaly occurs

Assumptions

- **Known:**
 - Resources and capacities
 - Robots
 - CNC machines
 - Pallets
 - Events that acquire & release resources
- **Measurable:**
 - Event logs
 - Communication between controllers (OPC tag changes)
- **Unknown:**
 - Formal model of the system
Could be constructed but is time-consuming and error prone
 - Logic control code
Written by different people at different times in different languages
 - Correct event order
Many different orders may be acceptable

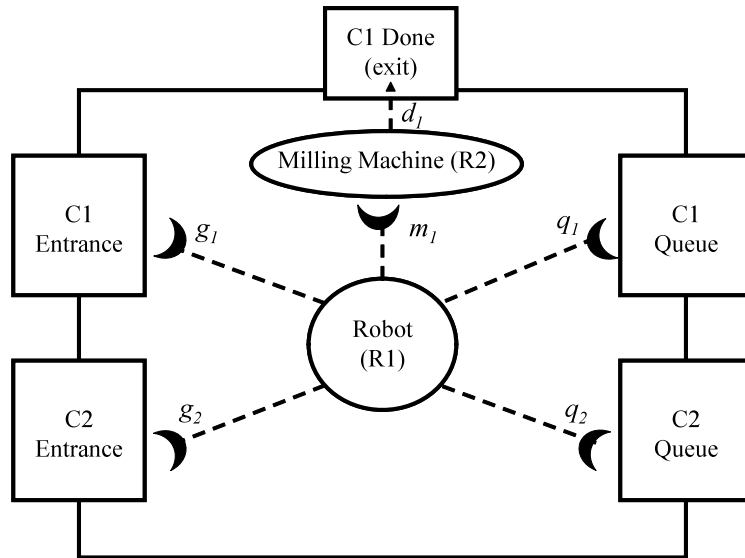
Prior work on fault detection

Existing approaches	Our approach
<ul style="list-style-type: none">• Machine-level faults• Continuous data• Require pre-existing formal model• Require fault models• Require system knowledge, e.g. max # of places in Petri net• No decisions based on resource availability	<ul style="list-style-type: none">• System-level faults• Event-based data• No pre-existing formal model• No model of faults• No <i>a priori</i> limit on size of system model• Readily-available system information included

SPSR = System of Processes that interact through Shared Resources

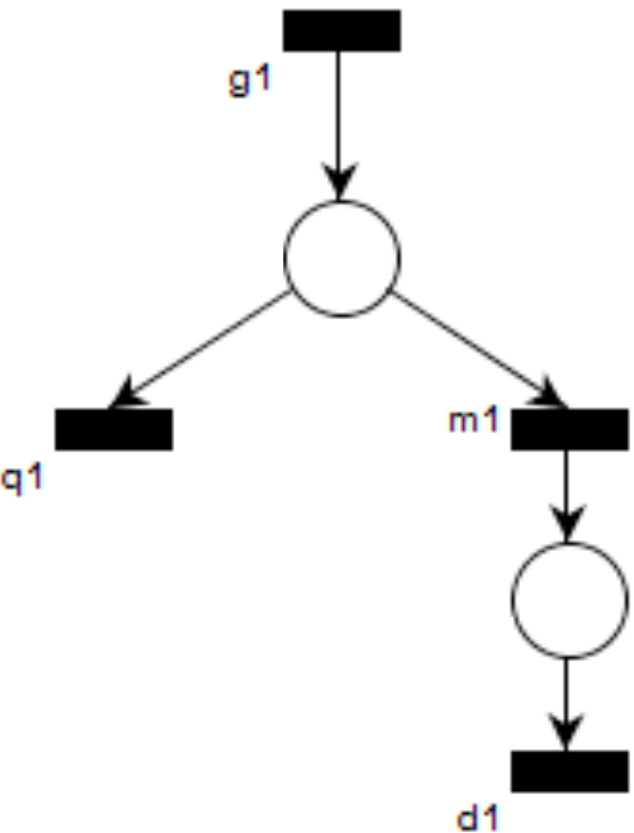
- **Resource – robot, CNC, pallet, etc.**
 - Acquired and released by known **events**
 - Capacity of each resource is known
- **Process = set of events and resources**
 - Processes interact to accomplish a goal
 - Modular (separate, independent)
 - **Interact only through shared resources**

Example: Resources and events



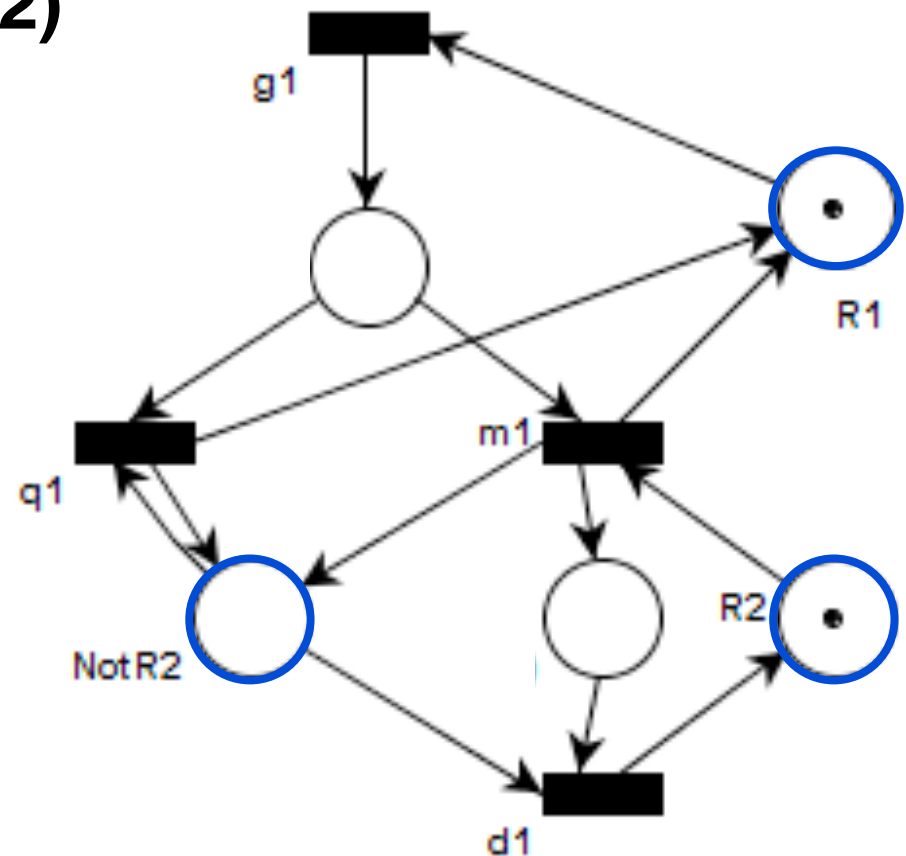
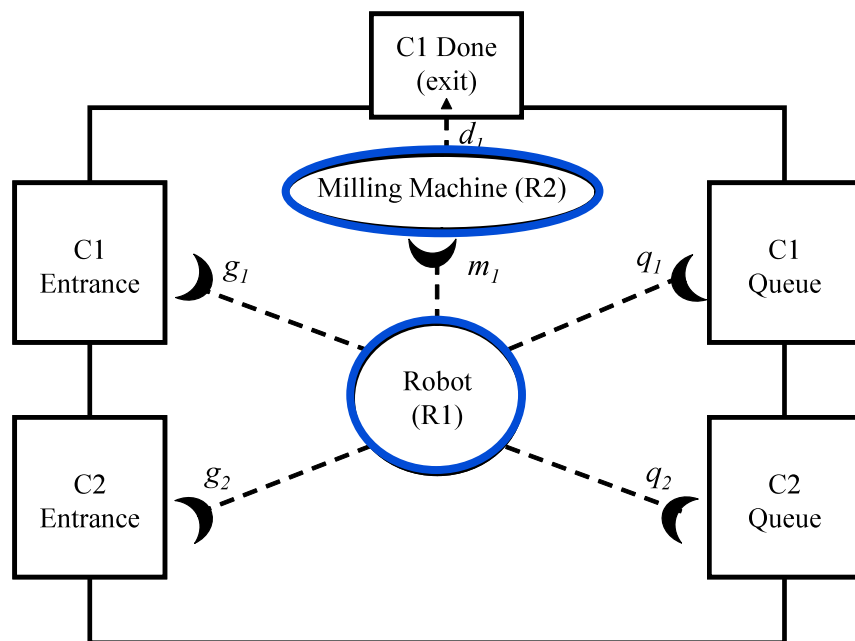
	Acquire	Release
R1 (Robot)	g_1, g_2	m_1, q_1, q_2
R2 (Machine)	m_1	d_1

- **Process 1**
 - Events g_1, q_1, m_1, d_1
- **Process 2**
 - Events g_2, q_2
- **Resources**
 - Robot; shared by both processes
 - Milling machine, only for process 1

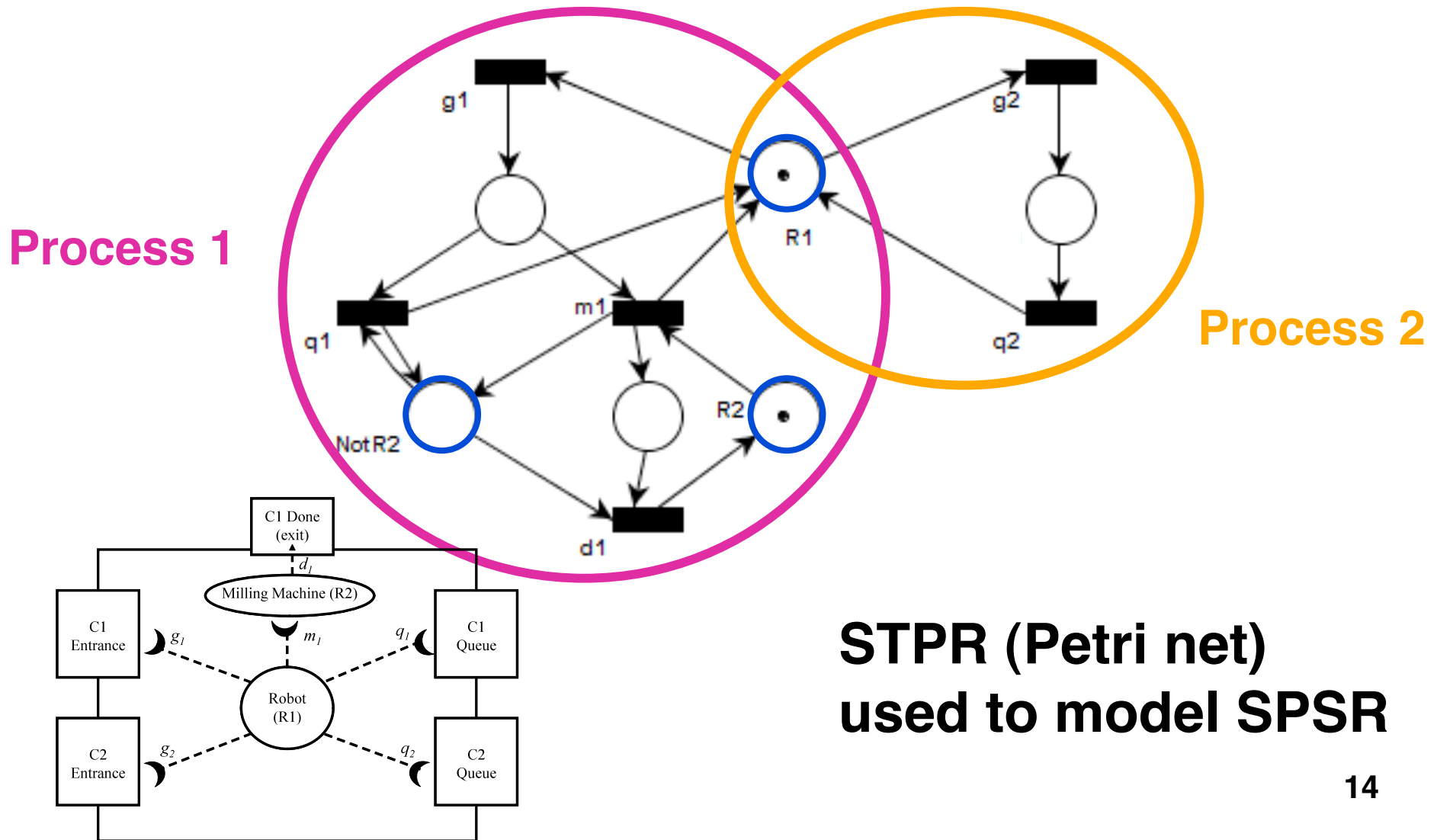


Transition Process with Resources

- Decision to mill or queue based on availability of mill (R2)



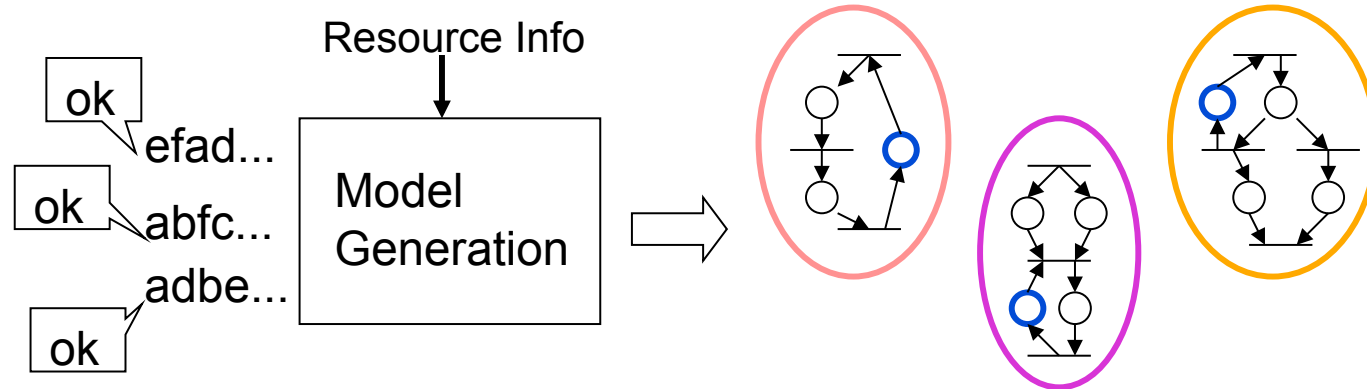
Systems of Transition Processes with Resources (STPRs)



Outline

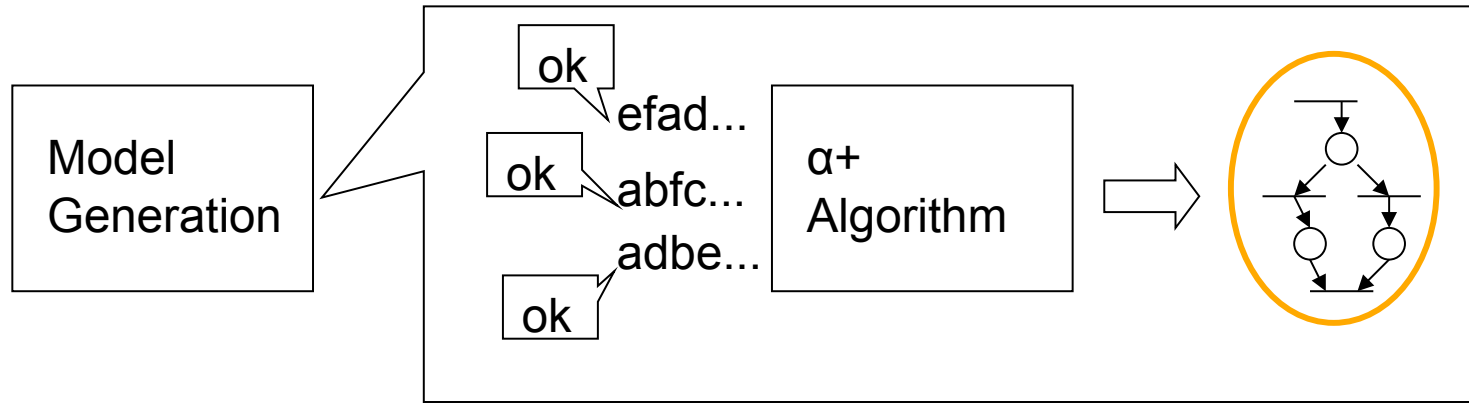
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Model Generation



- **Input: normal event streams, resource info**
- **Create models of each process**
- **Connect process models via shared resources**
- **Output: models of whole system**

Create individual process models



- **Determine process-specific event relationships**
- **Create process models (α^+ algorithm)**
 - Variations considering other process events
 - Add resource information to models

α + algorithm for process models

- **Event ordering relationships**
 - Causal if ab but not ba (\rightarrow)
 - Two-event loop if both aba and bab occur (\diamond)
 - Parallel if both ab and ba occur (\parallel)
 - None if neither ab nor ba occurs ($\#$)
- **Creating places (events label transitions)**
 - Causal: One place from a to b
 - Loop: Two places connecting a and b
 - Parallel or None: No places created

Event pair relationships

$$\sigma_1 = g_1 m_1 g_1 d_1 m_1 d_1 g_1 m_1 g_1 q_1 g_1 q_1 g_2 d_1 q_2 g_1 m_1 g_2 d_1 q_2$$

$$\sigma_2 = g_2 q_2 g_1 m_1 g_1 q_1 d_1 g_2 q_2 g_2 q_2 g_1 m_1 g_2 q_2 g_1 d_1 m_1 g_1 d_1$$

- Number of occurrences of each pair

	g_1	m_1	d_1	q_1	g_2	q_2
g_1	0	5	3	3	0	0
m_1	4	0	1	0	2	0
d_1	1	2	0			
q_1	1	0	1			
g_2	0	0	2			
q_2	4	0	0			

Gray shaded events belong to process 1

- Relationships between pairs

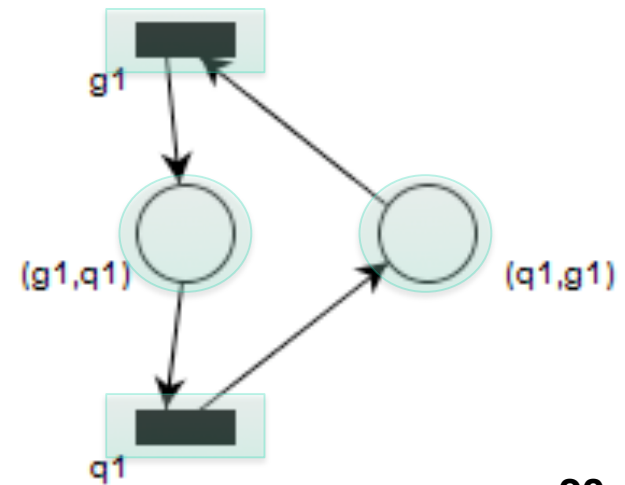
	g_1	m_1	d_1	q_1	g_2	q_2
g_1	#			◇	#	←
m_1		#		#	→	#
d_1			#	←		→
q_1	◇	#	→	#	→	#
g_2	#	←		←	#	◇
q_2	→	#	←	#	◇	#

Example pair: 2-event loop

$$\sigma_1 = g_1 m_1 g_1 d_1 m_1 d_1 g_1 m_1 \mathbf{g_1 q_1 g_1 q_1} g_2 d_1 q_2 g_1 m_1 g_2 d_1 q_2$$

$$\sigma_2 = g_2 q_2 g_1 m_1 \mathbf{g_1 q_1} d_1 g_2 q_2 g_2 q_2 g_1 m_1 g_2 q_2 g_1 d_1 m_1 g_1 d_1$$

- $\mathbf{g_1 q_1 g_1}$ and $\mathbf{q_1 g_1 q_1}$ both occur
- $g_1 \diamond q_1$ (two-event loop)
- One place to connect g_1 to q_1 and another place to connect q_1 to g_1



Example pair: Parallel

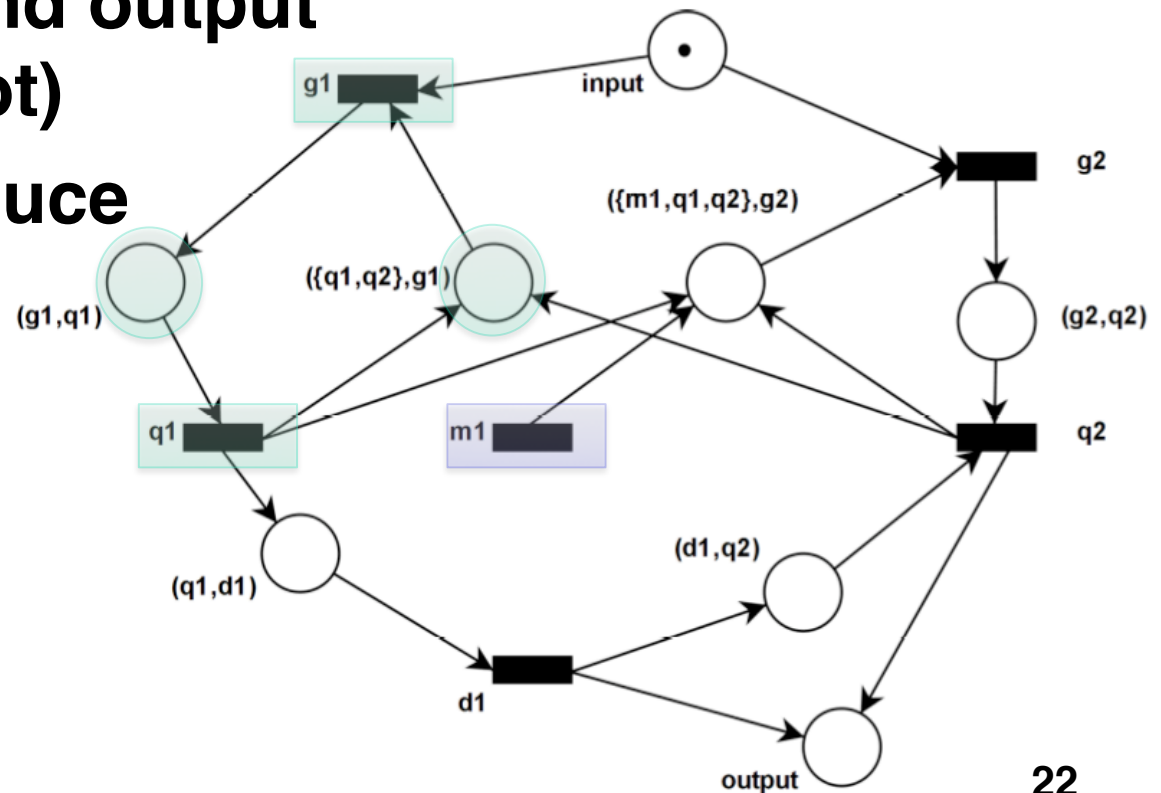
$$\sigma_1 = g_1 m_1 g_1 d_1 m_1 d_1 g_1 m_1 g_1 q_1 g_1 q_1 g_2 d_1 q_2 g_1 m_1 g_2 d_1 q_2$$

$$\sigma_2 = g_2 q_2 g_1 m_1 g_1 q_1 d_1 g_2 q_2 g_2 q_2 g_1 m_1 g_2 q_2 g_1 d_1 m_1 g_1 d_1$$

- $g_1 m_1$ Yes $m_1 g_1$ Yes $g_1 m_1 g_1$ Yes $m_1 g_1 m_1$ No
- $g_1 \parallel m_1$ (parallel)
- no places connecting

Output of $\alpha+$ algorithm

- Places created with \rightarrow and \diamond relationships
- Combining places where possible
- Single input and output place (one-shot)
- Cannot reproduce given traces
- Does not incorporate resource info

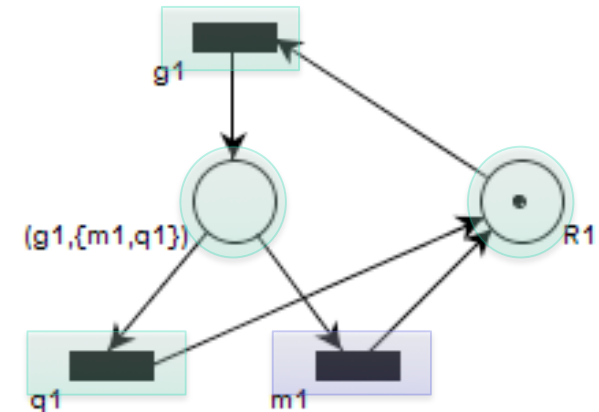


Model variations

- **Using only events from process 1 creates a single model for process 1**
- **Alternate models are created by:**
 - **Considering events from other processes**
 - **Considering resource relationships**
 - **Considering implicit event relationships (e.g., due to interleavings)**
- **Many variations created for each process**
 - **Multiple models for each process**
- **Process models are combined by joining shared resource places**

Example: Incorporating resources

- $g_1 \parallel m_1$ (no places connecting)
- Consider resource R1 (robot)
 - g_1 acquires R1
 - Both m_1 , q_1 release R1
 - Subtract resource relationship
- $g_1 \parallel m_1$ remove $m_1 \rightarrow g_1$ yields $g_1 \rightarrow m_1$
 - Add a place connecting g_1 to m_1
 - Combine places



Theorem: Re-create “true” model

- **If** the underlying “true” model
 - is a TP with certain properties (safe, live, etc.)
 - and **if** the given event log contains all possible event pairs and two-event loops
- **Then** one of the TP models created by the model generation algorithm will be the “true” TP model.
- **Implication:** If the underlying “true” model is an STPR whose TPs and event log meet these requirements, then one of the created STPR models exactly matches the “true” model.

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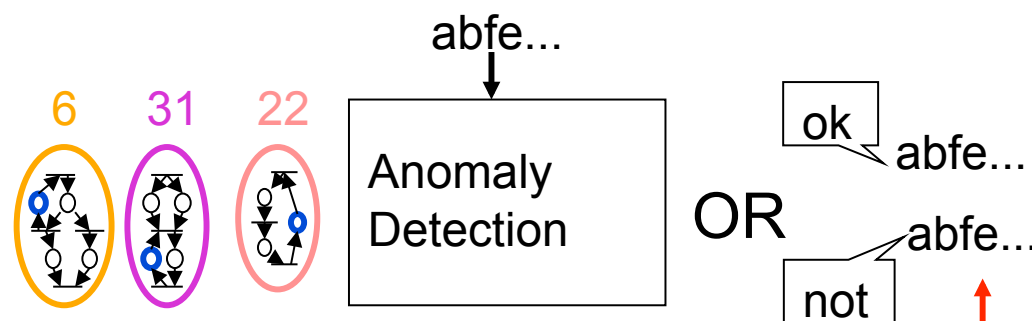
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Model Performance Assessment



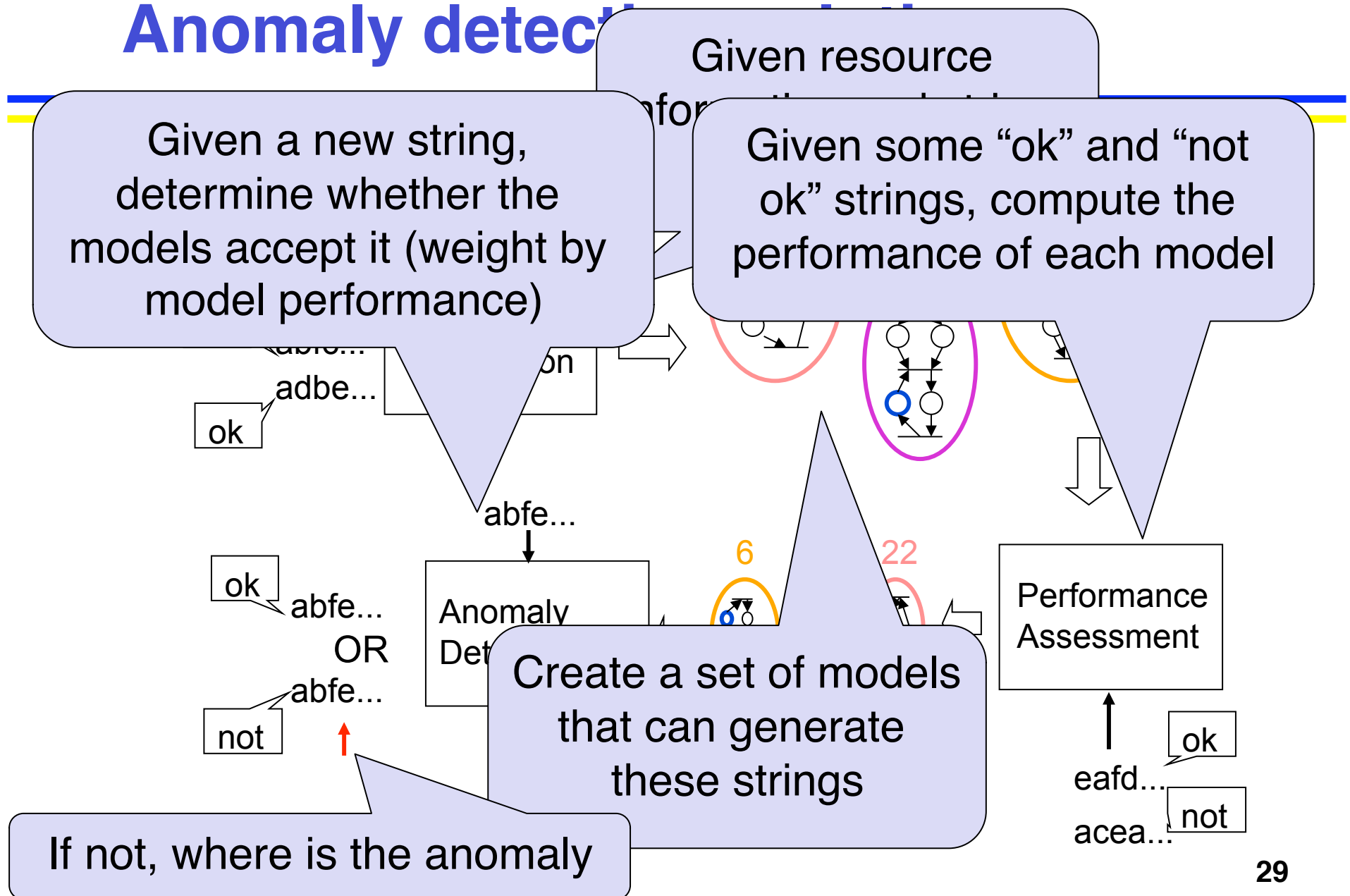
- **Input: models, labeled event streams**
- **Assess model performance based on labeled event streams**
 - Increase performance by 1 if correct
 - Decrease performance by 1 if incorrect
- **Output: performance of models**

Anomaly Detection



- **Input: models with their performances, unlabeled event stream**
- **Anomaly detection**
 - Determine whether models allow stream
 - Performance-weighted majority voting to decide whether anomaly in stream
- **Output: whether anomaly in stream, and if so, where first detected**

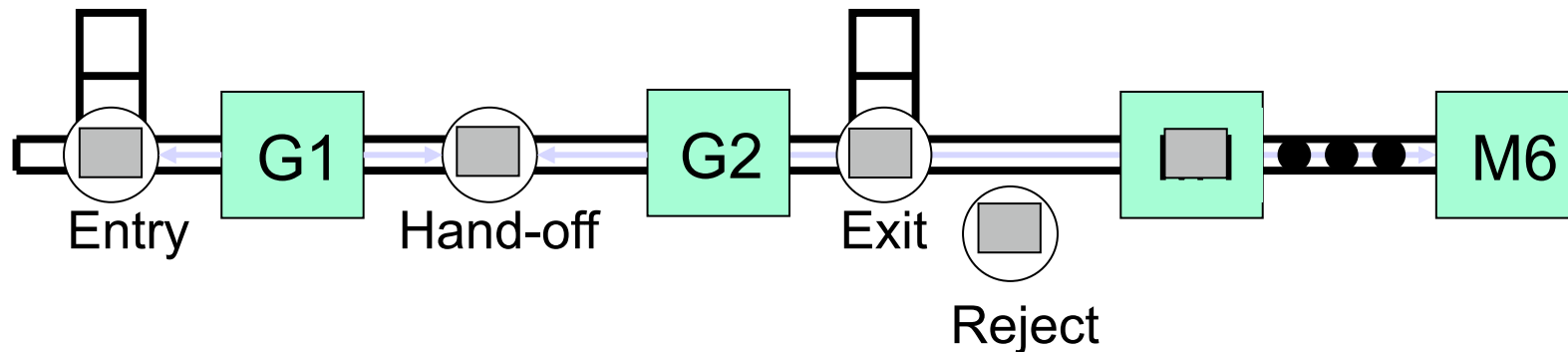
Anomaly detection



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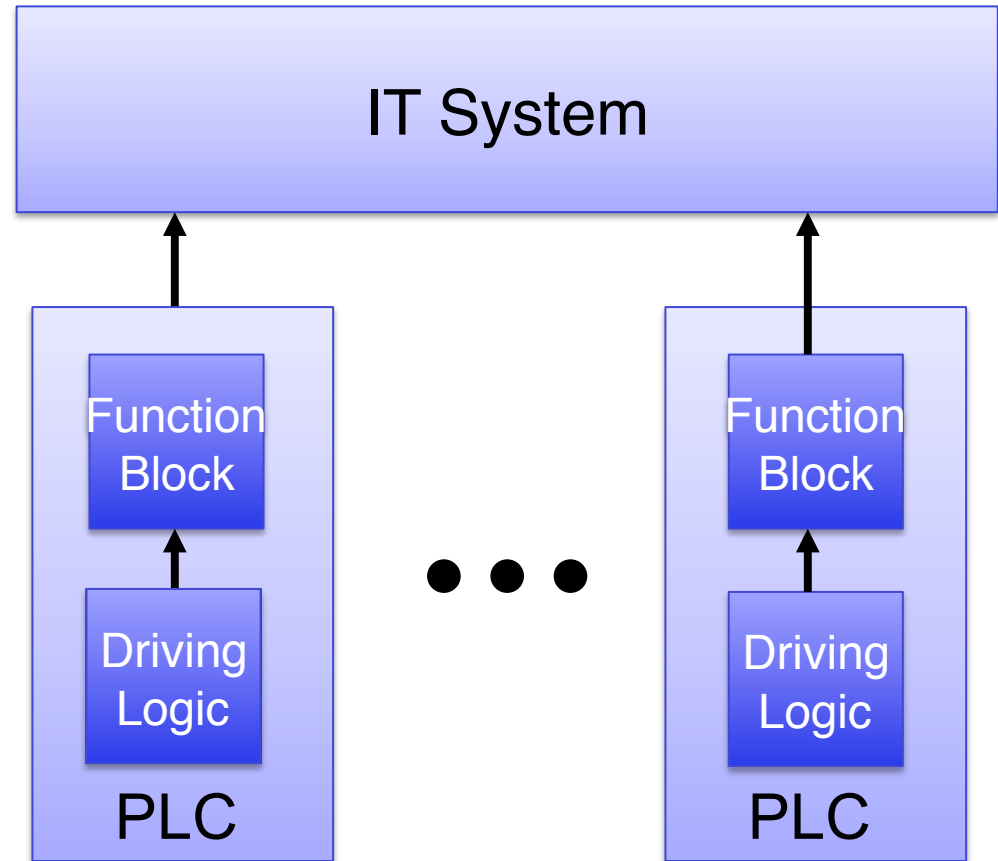
Machining Cell: Physical Set-Up



- **Problem:** G2 will have raw parts and at least one CNC available, but G2 incorrectly waits
- **Resources:**
 - gantries, Machines (CNC)
- **Processes:**
 - one per CNC, one for gantries

Data collection set-up

- **Data from each machine & gantry**
 - Bits include: Cycle End, Good/Bad Cycle, Wait Aux, Blocked, and Starved
 - PLC message generated each time particular bit changes occur
- **Approx. 11,000 parts worth of data (270,000 PLC messages)**



Application to industry data

- **What we thought we would get:**
 - Well-defined strings of events
 - Events that acquire/release resources recorded
 - Unique mapping of PLC bits to events
 - Many strings, starting from the initial state, labeled as “good” or “bad
- **What we got:**
 - Not every event triggers a message
→ multi-bit change (order is uncertain)
 - Not all resource events captured in data collection
 - Some bits used for multiple purposes
 - One huge Excel file with no defined “beginning”

Identified Inconsistencies

	Academic Assumptions	Industry Realities
1	Resource events available	Some events filtered in data collection
2	String of ordered events	Multiple bit changes per message possible
3	Consistent bit-meaning mapping	Inconsistent bit-meaning mapping
4	Event streams start in initial state	System runs continuously
5	Separate, labeled streams	Continuous, unlabeled stream

1) Acquire/Release Resources

- **Events that acquire and release resources are required for model-building**
- **Not all such events were recorded in the data collection system**
- **Potential solution: proxy events**
 - **Example: gantry picks up raw parts**
 - **Proxy: gantry begins unload/load CNC**
 - **Problem: Do not know when gantry is waiting**
- **Actual solution: Industry changed data collection system to record these events**

2) String of Ordered Events

- **Ordering of events not known; multiple bit changes (MBC) between PLC messages**
- **Possible causes of MBC**
 - Not all bit changes cause PLC messages
 - Multiple bits can change within one PLC scan
- **Potential solution: Treat each MBC as unique event**
 - Approximately 1/3 of messages are MBC
 - MBCs account for $> 5/6$ unique events
- **Actual solution: Split each MBC into sequence of single events**

3) Consistent bit mapping

- **Design documents define meaning of bits**
- **Implementation of PLC programming may result in slightly different use of bits**
- **Examples (occasional, inconsistent)**
 - **Cycle End bit pulsed high twice in a row**
 - **Wait Aux used for other other purposes besides machine interaction**
- **Potential solution: change logic to be consistent with design docs**
- **Actual solution: some logic changes, also pre-processed data for known issues**

4) Initial State

- **System is running continuously, rarely returns to “initial” state**
- **Problem: given event stream and STPR model, determine whether there exists a sequence of states in the model such that event stream could have occurred**
- **Solution: Define a necessary condition**
 - Lower bound based on events in stream
 - Upper bound based on resource conservation
 - If lower bound $<$ upper bound, stream is possible

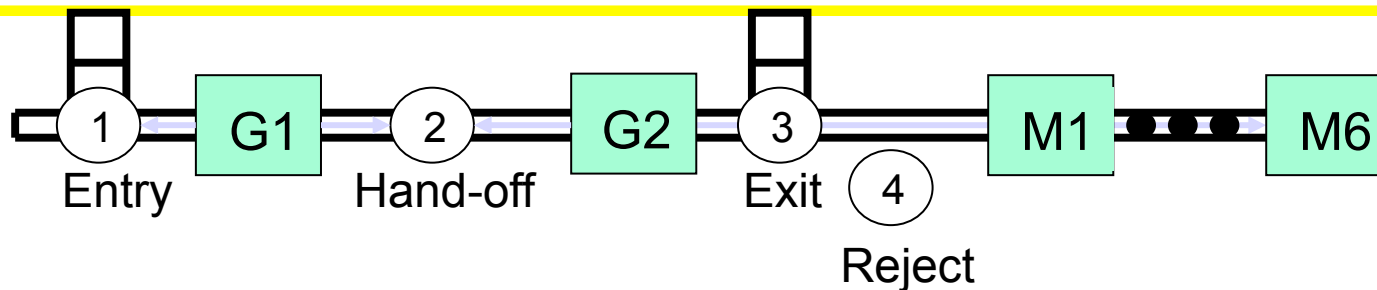
5) Separate Labeled Streams

- **Labeled streams needed**
 - Normal to create models
 - Normal & anomalous to assess model performance
- **Potential solution: System expert adds labels to streams**
- **Actual solution: Algorithm to split and label streams**
 - Split data into pre-set size streams
 - Label streams based on conditions on events that are known to be associated with problem(s)

Inconsistencies & Resolutions

	Academic Assumptions	Industry Realities	Resolution
1	Resource events available	Some events filtered in data collection	I: Logic changed
2	String of ordered events	Multiple bit changes per message possible	A: Heuristic decision algorithm
3	Consistent bit-meaning mapping	Inconsistent bit-meaning mapping	I, A: Logic changed, pre-process data
4	Event streams start in initial state	System runs continuously	A: Nec. condition to create stream
5	Separate, labeled streams	Continuous, unlabeled stream	A: Splitting, labeling algorithm

Machining cell: Data selection



- **8 PLCs each report 40 words (x16 bits) data**
 - **Appropriate events (bit rise/fall) must be chosen**

Resource	Events	Resource	Events
Gantry	Start waiting	CNCi	Blocked
	End waiting		Wait Aux
	Leave w/o waiting		Part not present
	Pick up raw part		Cycle end
	Part at inspection		
	Part at exit		
	Arrive at CNCi		

Building model from data

- One process for gantry, one for each CNC
- Exclude sections of data when gantry or CNC in “fault” state
- Add *CNCs Ready* resource as combination of all CNCs

Resources	Acquire	Release
Gantry G1	Pick up raw part	CNC wait aux fall
Gantry G2	Arrive at CNCi	Part at exit; inspection
Mi (CNCi)	CNC cycle end rise	CNC part unload
<i>CNCs Ready</i>	Gantry end waiting	CNC blocked

Sample
model with
one CNC
process

-

Gantry waiting: word
19 bit 9 is high

Gantry →
CNC3

Gantry →
CNC1

Gantry →
CNC2

Gantry →
CNC3

44

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Conclusions & Future Work

- **Anomaly detection in event-based systems without a formal model**
 - Information on resources, processes & events
- **Multiple process models built to cope with uncertainty about true behavior of system**
 - Number of “whole” models can be quite large
 - Maintaining modularity through performance assessment phase could reduce complexity
- **Application to off-line data**
 - On-line detection could be implemented
 - On-line model building could consider and evaluate multiple different sets of events

Acknowledgements

- **NSF Engineering Research Center for Reconfigurable Manufacturing Systems at the University of Michigan**
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